

## Patent claims

1. A circuit arrangement for compensating for disturbances in a signal generated by means of discrete multitone modulation (DMT), the signal generated by means of discrete multitone modulation exhibiting in the frequency domain a multiplicity of carrier frequencies which are used for transmitting data via a transmission channel, and each carrier frequency exhibiting a signal vector  $(a_1', b_1'; a_n, b_n')$ , comprising
- a multiplicity of first adder circuits (18, 19; 18-1, 19-1), the multiplicity of first adder circuits (18, 19; 18-1, 19-1) being supplied with a first error signal vector and the multiplicity of first adder circuits (18, 19; 18-1, 19-1) adding the first error signal vector to at least one first signal vector  $(a_n', b_n'; a_1', b_1')$  in order to generate an error-corrected first signal vector  $(a_n^*, b_n^*; a_n^*-1, b_n^*-1; a_1^*, b_1^*)$ ; and
  - a multiplicity of first multiplier circuits (14, 15, 16, 17; 14-1, 15-1, 16-1, 17-1) which precede the multiplicity of first adder circuits (18, 19; 18-1, 19-1) and multiply the first error signal vector by adjustable coefficients  $(C_{aa}^{(n)}, C_{ba}^{(n)}, C_{bb}^{(n)}, C_{ab}^{(n)}; C_{aa}^{(1,n)}, C_{ba}^{(1,n)}, C_{bb}^{(1,n)}, C_{ab}^{(1,n)}; C_{aa}^{(1)}, C_{ba}^{(1)}, C_{bb}^{(1)}, C_{ab}^{(1)}; C_{aa}^{(n,1)}, C_{ba}^{(n,1)}, C_{bb}^{(n,1)}, C_{ab}^{(n,1)})$ , wherein the first error signal vector is a signal vector  $(a_r, b_r; a_{1r}, b_{1r}; a_{r-1}, b_{r-1})$  of a carrier frequency which is not used for transmitting data via the transmission channel.
2. The circuit arrangement as claimed in claim 1, wherein the first error signal vector is a signal vector  $(a_r, b_r)$  of a carrier frequency which, in the frequency domain, is adjacent to a carrier frequency which is used for transmitting data via the transmission channel.

3. The circuit arrangement as claimed in claim 1 or 2, wherein the first error signal vector is a signal vector  $(a_r, b_r)$  of a carrier frequency which, in the frequency domain, immediately precedes a carrier frequency which  
 5 is used for transmitting data via the transmission channel.

4. The circuit arrangement as claimed in claim 1 or 2, wherein the circuit arrangement also exhibits the  
 10 following features:

- at least one further multiplicity of first adder circuits (18-2, 19-2 to 18-m, 19-m) which follow the multiplicity of first adder circuits (18, 19; 18-1, 19-1), the at least one further multiplicity of first adder  
 15 circuits (18-2, 19-2 to 18-m, 19-m) in each case being supplied with a further error signal vector  $(a_{2r}, b_{2r}$  to  $a_{mr}, b_{mr}; a_{r-2}, b_{r-2}, a_{r-3}, b_{r-3})$  and the at least one further multiplicity of first adder circuits (18-2, 19-2 to 18-m, 19-m) adding the respective further error  
 20 signal vector  $(a_{2r}, b_{2r}$  to  $a_{mr}, b_{mr}; a_{r-2}, b_{r-2}, a_{r-3}, b_{r-3})$  to the at least one signal vector  $(a_n', b_n')$  in order to generate a progressively error-corrected signal vector  $(a_n^{*-2}, b_n^{*-2}$  to  $a_n^{*-m}, b_n^{*-m})$ ; and

- at least one further multiplicity of first  
 25 multiplier circuits (14-2, 15-2, 16-2, 17-2 to 14-m, 15-m, 16-m, 17-m) which precede the at least one further multiplicity of first adder circuits (18-2, 19-2 to 18-m, 19-m) and multiply the respective further error signal vector  $(a_{2r}, b_{2r}$  to  $a_{mr}, b_{mr}; a_{r-2}, b_{r-2}, a_{r-3}, b_{r-3})$   
 30 by adjustable coefficients  $(C_{aa}^{(2,n)}, C_{ba}^{(2,n)}, C_{bb}^{(2,n)}, C_{ab}^{(2,n)}$  to  $C_{aa}^{(m,n)}, C_{ba}^{(m,n)}, C_{bb}^{(m,n)}, C_{ab}^{(m,n)}$ ;  $C_{aa}^{(n,2)}, C_{ba}^{(n,2)}, C_{bb}^{(n,2)}, C_{ab}^{(n,2)})$ .

5. The circuit arrangement as claimed in claim 4,  
 35 wherein the respective further error signal vector is in each case a signal vector  $(a_{2r}, b_{2r}$  to  $a_{mr}, b_{mr})$  of a

carrier frequency which is not used for transmitting data via the transmission channel.

6. The circuit arrangement as claimed in claim 4 or 5, wherein the respective further error signal vector ( $a_{r-2}$ ,  $b_{r-2}$ ,  $a_{r-3}$ ,  $b_{r-3}$ ) is in each case a previous version of a particular error signal vector ( $a_{r-1}$ ,  $b_{r-1}$ ).

7. The circuit arrangement as claimed in claim 6, wherein the circuit arrangement has at least one buffer circuit (20-1, 20-2) for storing a previous version of an error signal vector ( $a_{r-1}$ ,  $b_{r-1}$ ).

8. The circuit arrangement as claimed in claim 1, 2 or 3, wherein the circuit arrangement also exhibits the following features:

- a decision circuit (4-1) which maps the error-corrected first signal vector ( $a_1^*$ ,  $b_1^*$ ) into a value-discrete first signal vector ( $a_1''$ ,  $b_1''$ ); and
- a subtracting circuit (6-1, 7-1) for forming a second error signal vector ( $\Delta a_1$ ,  $\Delta b_1$ ) which subtracts the first signal vector ( $a_1'$ ,  $b_1'$ ) and the value-discrete first signal vector ( $a_1''$ ,  $b_1''$ ) from one another, the second error signal vector ( $\Delta a_1$ ,  $\Delta b_1$ ) being used for generating an error-corrected second signal vector ( $a_2^*$ ,  $b_2^*$ ) of a second signal vector ( $a_2'$ ,  $b_2'$ ) of a carrier frequency which is immediately adjacent to the carrier frequency of the first signal vector ( $a_1'$ ,  $b_1'$ ).

9. The circuit arrangement as claimed in claim 8, wherein the circuit arrangement also exhibits the following features:

- a multiplicity of second adder circuits (12-1, 13-1), the multiplicity of second adder circuits (12-1, 13-1) being supplied with the second error signal vector ( $\Delta a_1$ ,  $\Delta b_1$ ) and the multiplicity of second adder circuits

(12-1, 13-1) adding the second error signal vector ( $\Delta a_1$ ,  $\Delta b_1$ ) to the second signal vector ( $a_2'$ ,  $b_2'$ ) in order to generate the error-corrected second signal vector ( $a_2^*$ ,  $b_2^*$ ); and

- 5 - a multiplicity of second multiplier circuits (8-1, 9-1, 10-1, 11-1) which precede the multiplicity of second adder circuits (12-1, 13-1) and multiply the second error signal vector ( $\Delta a_1$ ,  $\Delta b_1$ ) by adjustable coefficients ( $C_{aa}^{(2)}$ ,  $C_{ba}^{(2)}$ ,  $C_{bb}^{(2)}$ ,  $C_{ab}^{(2)}$ ).

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10. The circuit arrangement as claimed in claim 9, wherein the circuit arrangement also exhibits the following features:

- 15 - a further decision circuit (4-2) which maps the error-corrected second signal vector ( $a_2^*$ ,  $b_2^*$ ) into a value-discrete second signal vector ( $a_2''$ ,  $b_2''$ ); and

- a further subtracting circuit (6-2, 7-2) for forming a third error signal vector ( $\Delta a_2$ ,  $\Delta b_2$ ) which subtracts the second signal vector ( $a_2'$ ,  $b_2'$ ) and the value-discrete second signal vector ( $a_2''$ ,  $b_2''$ ) from one another,

20 the third error signal vector ( $\Delta a_2$ ,  $\Delta b_2$ ) being used for generating an error-corrected third signal vector ( $a_3^*$ ,  $b_3^*$ ) of a third signal vector ( $a_3'$ ,  $b_3'$ ) of a carrier frequency which is immediately adjacent to the carrier frequency of the second signal vector ( $a_2'$ ,  $b_2'$ ).

11. A circuit arrangement for compensating for disturbances in a signal generated by means of discrete multitone modulation (DMT), the signal generated by means of discrete multitone modulation exhibiting in the frequency domain a multiplicity of carrier frequencies which are used for transmitting data via a transmission channel, and each carrier frequency exhibiting a signal vector ( $a_1'$ ,  $b_1'$ ;  $a_n'$ ,  $b_n'$ ), comprising

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- decision circuits which are in each case supplied with a reference signal vector  $(a_{1r}, b_{1r} \text{ to } a_{mr}, b_{mr})$  and which map the respective reference signal vector  $(a_{1r}, b_{1r} \text{ to } a_{mr}, b_{mr})$  into a respective value-discrete reference signal vector;
- subtracting circuits for forming a respective error signal vector which subtract the respective reference signal vector  $(a_{1r}, b_{1r} \text{ to } a_{mr}, b_{mr})$  and the respective value-discrete reference signal vector from one another;
- groups of first adder circuits  $(18-1, 19-1 \text{ to } 18-m, 19-m)$ , each group of first adder circuits  $(18-1, 19-1 \text{ to } 18-m, 19-m)$  in each case being supplied with an error signal vector and the groups of first adder circuits  $(18-1, 19-1 \text{ to } 18-m, 19-m)$  adding the respective error signal vector to at least one signal vector  $(a_n', b_n'; a_1', b_1')$  in order to generate a progressively error-corrected signal vector  $(a_n^{*-1}, b_n^{*-1} \text{ to } a_n^{*-m}, b_n^{*-m})$ ; and
- groups of first multiplier circuits  $(14-1, 15-1, 16-1, 17-1 \text{ to } 14-m, 15-m, 16-m, 17-m)$  which in each case precede a group of first adder circuits  $(18-1, 19-1 \text{ to } 18-m, 19-m)$  and multiply the respective error signal vector by adjustable coefficients  $(C_{aa}^{(1,n)}, C_{ba}^{(1,n)}, C_{bb}^{(1,n)}, C_{ab}^{(1,n)} \text{ to } C_{aa}^{(m,n)}, C_{ba}^{(m,n)}, C_{bb}^{(m,n)}, C_{ab}^{(m,n)})$ .

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12. The circuit arrangement as claimed in one of the preceding claims, wherein the adjustable coefficients can be adjusted by means of a correcting variable.

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13. The circuit arrangement as claimed in claim 12, wherein a power of 2 is selected for the correcting variable.

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14. A method for compensating for disturbances in a signal generated by means of discrete multitone modulation (DMT), the signal generated by means of

discrete multitone modulation exhibiting in the frequency domain a multiplicity of carrier frequencies which are used for transmitting data via a transmission channel, and each carrier frequency exhibiting a signal vector ( $a_1'$ ,  $b_1'$ ;  $a_n'$ ,  $b_n'$ ), comprising the following steps:

- multiplying at least one error signal vector by adjustable coefficients ( $C_{aa}^{(n)}$ ,  $C_{ba}^{(n)}$ ,  $C_{bb}^{(n)}$ ,  $C_{ab}^{(n)}$ ;  $C_{aa}^{(1,n)}$ ,  $C_{ba}^{(1,n)}$ ,  $C_{bb}^{(1,n)}$ ,  $C_{ab}^{(1,n)}$ ;  $C_{aa}^{(1)}$ ,  $C_{ba}^{(1)}$ ,  $C_{bb}^{(1)}$ ,  $C_{ab}^{(1)}$ ;  $C_{aa}^{(n,1)}$ ,  $C_{ba}^{(n,1)}$ ,  $C_{bb}^{(n,1)}$ ,  $C_{ab}^{(n,1)}$ ; and
- adding the at least one error signal vector multiplied by the adjustable coefficients to at least one signal vector ( $a_n'$ ,  $b_n'$ ;  $a_1'$ ,  $b_1'$ ) in order to generate an error-corrected signal vector ( $a_n^*$ ,  $b_n^*$ ;  $a_n^*-1$ ,  $b_n^*-1$ ;  $a_1^*$ ,  $b_1^*$ ), wherein the at least one error signal vector is a signal vector ( $a_r$ ,  $b_r$ ;  $a_{1r}$ ,  $b_{1r}$ ;  $a_{r-1}$ ,  $b_{r-1}$ ) of a carrier frequency which is not used for transmitting data via the transmission channel.

15. The method as claimed in claim 14, wherein the first error signal vector is a signal vector ( $a_r$ ,  $b_r$ ) of a carrier frequency which, in the frequency domain, is adjacent to a carrier frequency which is used for transmitting data via the transmission channel.

16. The method as claimed in claim 14 or 15, wherein the first error signal vector is a signal vector ( $a_r$ ,  $b_r$ ) of a carrier frequency which, in the frequency domain, immediately precedes a carrier frequency which is used for transmitting data via the transmission channel.

17. The method as claimed in claim 14 or 15, wherein the method also exhibits the following steps:

- multiplying a respective further error signal vector ( $a_{2r}$ ,  $b_{2r}$  to  $a_{mr}$ ,  $b_{mr}$ ;  $a_{r-2}$ ,  $b_{r-2}$ ,  $a_{r-3}$ ,  $b_{r-3}$ ) by adjustable coefficients ( $C_{aa}^{(2,n)}$ ,  $C_{ba}^{(2,n)}$ ,  $C_{bb}^{(2,n)}$ ,  $C_{ab}^{(2,n)}$

to  $C_{aa}^{(m,n)}$ ,  $C_{ba}^{(m,n)}$ ,  $C_{bb}^{(m,n)}$ ,  $C_{ab}^{(m,n)}$ ;  $C_{aa}^{(n,2)}$ ,  $C_{ba}^{(n,2)}$ ,  $C_{bb}^{(n,2)}$ ,  $C_{ab}^{(n,2)}$ ; and

- adding the respective further error signal vector ( $a_{2r}$ ,  $b_{2r}$  to  $a_{mr}$ ,  $b_{mr}$ ;  $a_{r-2}$ ,  $b_{r-2}$ ,  $a_{r-3}$ ,  $b_{r-3}$ ) multiplied by the adjustable coefficients ( $C_{aa}^{(2,n)}$ ,  $C_{ba}^{(2,n)}$ ,  $C_{bb}^{(2,n)}$ ,  $C_{ab}^{(2,n)}$  to  $C_{aa}^{(m,n)}$ ,  $C_{ba}^{(m,n)}$ ,  $C_{bb}^{(m,n)}$ ,  $C_{ab}^{(m,n)}$ ;  $C_{aa}^{(n,2)}$ ,  $C_{ba}^{(n,2)}$ ,  $C_{bb}^{(n,2)}$ ,  $C_{ab}^{(n,2)}$ ) to the at least one signal vector ( $a_n'$ ,  $b_n'$ ) in order to generate a progressively error-corrected signal vector ( $a_n^{*-2}$ ,  $b_n^{*-2}$ , to  $a_n^{*-m}$ ,  $b_n^{*-m}$ ).

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18. The method as claimed in claim 17, wherein the respective further error signal vector is in each case a signal vector ( $a_{2r}$ ,  $b_{2r}$  to  $a_{mr}$ ,  $b_{mr}$ ) of a carrier frequency which is not used for transmitting data via the transmission channel.

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19. The method as claimed in claim 17 or 18, wherein the respective further error signal vector ( $a_{r-2}$ ,  $b_{r-2}$ ,  $a_{r-3}$ ,  $b_{r-3}$ ) is in each case a previous version of a particular error signal vector ( $a_{r-1}$ ,  $b_{r-1}$ ).

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20. The method as claimed in claim 14, 15 or 16, wherein the method also exhibits the following steps:

- mapping the error-corrected first signal vector ( $a_1^*$ ,  $b_1^*$ ) into a value-discrete first signal vector ( $a_1''$ ,  $b_1''$ ); and
- subtracting the first signal vector ( $a_1'$ ,  $b_1'$ ) and the value-discrete first signal vector ( $a_1''$ ,  $b_1''$ ) from one another in order to form a second error signal vector ( $\Delta a_1$ ,  $\Delta b_1$ ), the second error signal vector ( $\Delta a_1$ ,  $\Delta b_1$ ) being used for generating an error-corrected second signal vector ( $a_2^*$ ,  $b_2^*$ ) of a second signal vector ( $a_2'$ ,  $b_2'$ ) of a carrier frequency which is immediately adjacent to the carrier frequency of the first signal vector ( $a_1'$ ,  $b_1'$ ).

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21. The method as claimed in claim 20, wherein the method also exhibits the following steps:

- multiplying the second error signal vector ( $\Delta a_1$ ,  $\Delta b_1$ ) by adjustable coefficients ( $C_{aa}^{(2)}$ ,  $C_{ba}^{(2)}$ ,  $C_{bb}^{(2)}$ ,  $C_{ab}^{(2)}$ ); and
- adding the second error signal vector ( $\Delta a_1$ ,  $\Delta b_1$ ) multiplied by the adjustable coefficients ( $C_{aa}^{(2)}$ ,  $C_{ba}^{(2)}$ ,  $C_{bb}^{(2)}$ ,  $C_{ab}^{(2)}$ ) to the second signal vector ( $a_2'$ ,  $b_2'$ ) in order to generate the error-corrected second signal vector ( $a_2^*$ ,  $b_2^*$ ).

22. The method as claimed in claim 21, wherein the method also exhibits the following steps:

- mapping the error-corrected second signal vector ( $a_2^*$ ,  $b_2^*$ ) into a value-discrete second signal vector ( $a_2''$ ,  $b_2''$ ); and
- subtracting the second signal vector ( $a_2'$ ,  $b_2'$ ) and the value-discrete second signal vector ( $a_2''$ ,  $b_2''$ ) from one another in order to form a third error signal vector ( $\Delta a_2$ ,  $\Delta b_2$ ), the third error signal vector ( $\Delta a_2$ ,  $\Delta b_2$ ) being used for generating an error-corrected third signal vector ( $a_3^*$ ,  $b_3^*$ ) of a third signal vector ( $a_3'$ ,  $b_3'$ ) of a carrier frequency which is immediately adjacent to the carrier frequency of the second signal vector ( $a_2'$ ,  $b_2'$ ).

23. A method for compensating for disturbances in a signal generated by means of discrete multitone modulation (DMT), the signal generated by means of discrete multitone modulation exhibiting in the frequency domain a multiplicity of carrier frequencies which are used for transmitting data via a transmission channel, and each carrier frequency exhibiting a signal vector ( $a_1'$ ,  $b_1'$ ;  $a_n'$ ,  $b_n'$ ), comprising the following steps:



- mapping a respective reference signal vector ( $a_{1r}$ ,  $b_{1r}$  to  $a_{mr}$ ,  $b_{mr}$ ) into a respective value-discrete reference signal vector;
- subtracting the respective reference signal vector  
5 ( $a_{1r}$ ,  $b_{1r}$  to  $a_{mr}$ ,  $b_{mr}$ ) and the respective value-discrete reference signal vector from one another in order to form a respective error signal vector;
- multiplying the respective error signal vector by adjustable coefficients ( $C_{aa}^{(1,n)}$ ,  $C_{ba}^{(1,n)}$ ,  $C_{bb}^{(1,n)}$ ,  $C_{ab}^{(1,n)}$   
10 to  $C_{aa}^{(m,n)}$ ,  $C_{ba}^{(m,n)}$ ,  $C_{bb}^{(m,n)}$ ,  $C_{ab}^{(m,n)}$ ); and
- adding the respective error signal vector multiplied by the adjustable coefficients ( $C_{aa}^{(1,n)}$ ,  $C_{ba}^{(1,n)}$ ,  $C_{bb}^{(1,n)}$ ,  $C_{ab}^{(1,n)}$  to  $C_{aa}^{(m,n)}$ ,  $C_{ba}^{(m,n)}$ ,  $C_{bb}^{(m,n)}$ ,  $C_{ab}^{(m,n)}$ )  
15 to at least one signal vector ( $a_n'$ ,  $b_n'$ ;  $a_1'$ ,  $b_1'$ ) in order to generate a progressively error-corrected signal vector ( $a_n^{*-1}$ ,  $b_n^{*-1}$  to  $a_n^{*-m}$ ,  $b_n^{*-m}$ ).

24. The method as claimed in one of claims 14 to 23,  
20 wherein the adjustable coefficients can be adjusted by means of a correcting variable.

25. The method as claimed in claim 24, wherein a power of 2 is selected for the correcting variable.